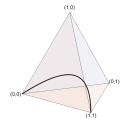
Multi-Observation Elicitation



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Background: Properties of distributions

Property or *statistic* of a probability distribution:

 $\Gamma: \Delta_{\mathcal{Y}} \to \mathcal{R}$

Examples:

$$\begin{split} & \Gamma(p) = \mathbb{E}_{Y \sim p} Y & \text{mean} \\ & \Gamma(p) = \sum_{y} p(y) \log \frac{1}{p(y)} & \text{entropy} \\ & \Gamma(p) = \operatorname{argmax}_{y} p(y) & \text{mode} \\ & \Gamma(p) = \mathbb{E}_{Y \sim p} (Y - \mathbb{E} Y)^2 & \text{variance} \end{split}$$

If we minimize expected loss, what do we get?

If we minimize **expected loss** under a distribution p, what **property** of p do we get?

$$r^* = \mathop{\mathrm{argmin}}_{r \in \mathcal{R}} \quad \mathop{\mathbb{E}}_{Y \sim p} \ell(r, Y) \qquad \qquad \text{minimize loss}$$

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Motivation: statistically consistent losses.

- Finite property space: classification, ranking, ...
- $\Gamma(p) \in \mathbb{R}^d$: regression, ...

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Examples:

- The mean is elicited by squared loss.
- Variance: elicit mean and second moment, then link.
- Any property is a link from the whole distribution ... but dimension of prediction r is unbounded...

This paper

What if the loss takes **multiple** i.i.d. observations?

$$r^* = \underset{r \in \mathcal{R}}{\operatorname{argmin}} \quad \underset{Y_1, \dots, Y_m \sim p}{\mathbb{E}} \ell(r, Y_1, \dots, Y_m)$$

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Examples:

- Var(p) = argmin_r $\mathbb{E}\left(r \frac{1}{2}(Y_1 Y_2)^2\right)^2$.
 - 2-norm: unbounded dimension \rightarrow 1 dimension, 2 observations!

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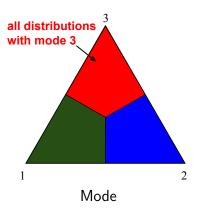
Motivating applications:

- Crowd labeling
- Numerical simulations climate science, engineering, ...
- Regression?

Key concepts from prior research

Elicitable properties have convex level sets, linear structures.

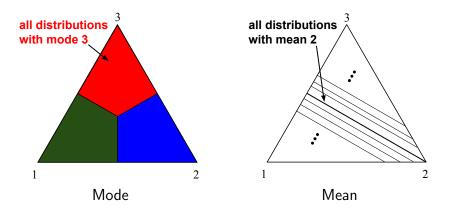
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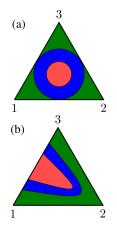
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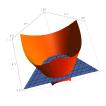
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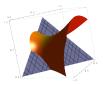


Results (1) Geometric approach

Summary: k-observation level sets \leftrightarrow zeros of degree-k polynomials







Results (2) Upper and lower bounds.

Key example: (integer) k-norm
$$(p) = \left(\sum_y p(y)^k\right)^{1/k}$$
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Idea: $\mathbf{1}[Y_1 = \cdots = Y_k]$ is an **unbiased estimator** for $||p||_k^k$.

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Loss
$$(r, Y_1, ..., Y_k) = (r - \mathbf{1}[Y_1 - \dots = Y_k])^2$$
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Link $(r) = r^{1/k}$.

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- Similar approach for products of expectations.
- Lower bound: k-norm requires k observations.
- Lower bound approach is general (algebraic geometry).

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Why could this be useful?

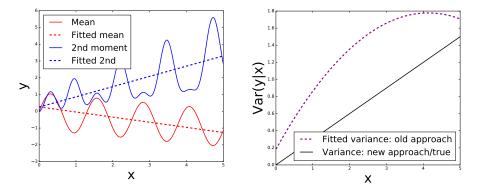
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 \implies Requires good modeling and sufficient data for these (unimportant) proxies!

Future directions

Elicitation frontiers and (d, m)-elicitability

In paper: central moments

Regression

In paper: preliminary results

Additional useful examples e.g. expected max of k draws; risk measures

Lots of COLT questions for multi-observation losses!

Thanks!



Aside - comparison to property testing

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Property Elicitation

- Existential questions, e.g....
- ... does there exist a one-dim. loss function eliciting variance? no
- ... two-dimensional?
- ... describe all losses directly eliciting the mean *divergences*

ves