

# Contracts with Information Acquisition, via Scoring Rules

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*TheoryFest*  
*June 2022*

**principal**



**agent**



principal



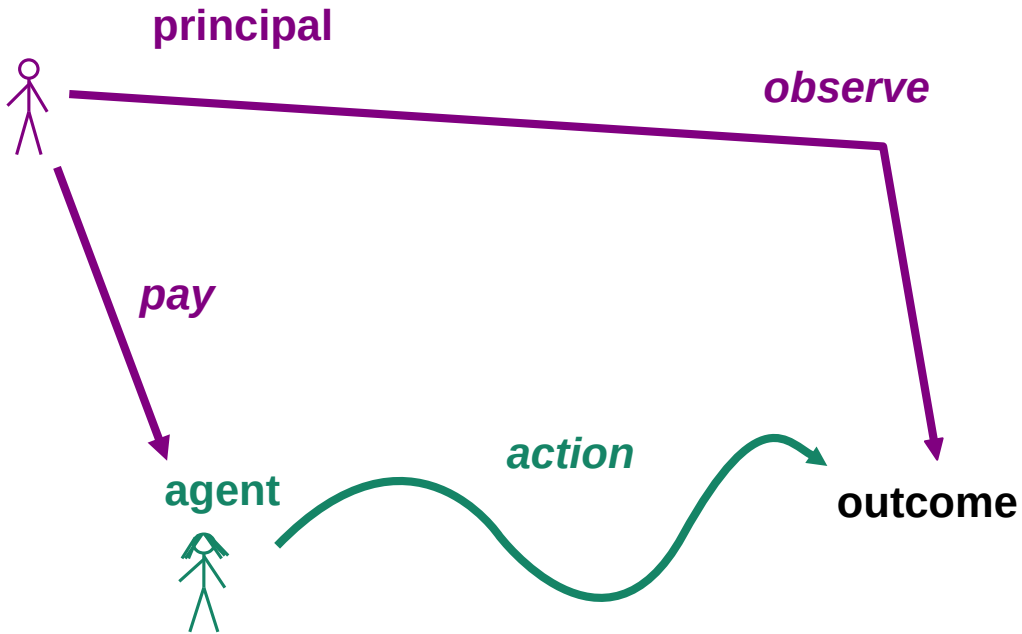
agent



*action*

**outcome**





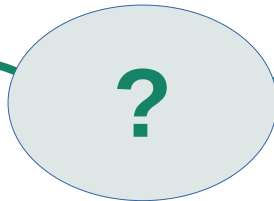
**principal**



**agent**

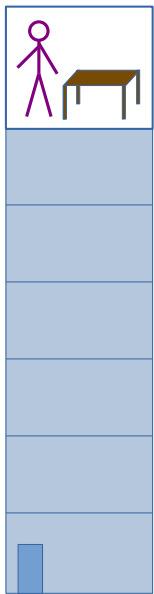


*hidden  
action*



**outcome**

principal



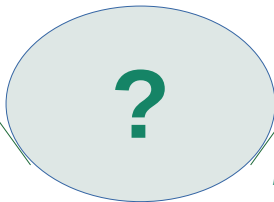
agent



1. Gather info.  
(or don't)



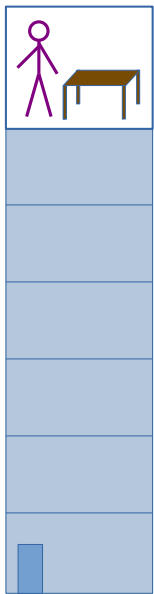
2. Choose an  
action



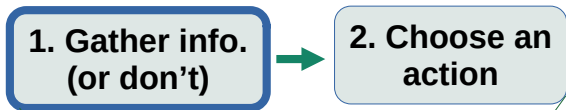
*hidden  
action*

outcome

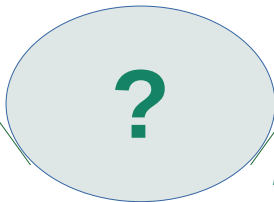
principal



New in this paper

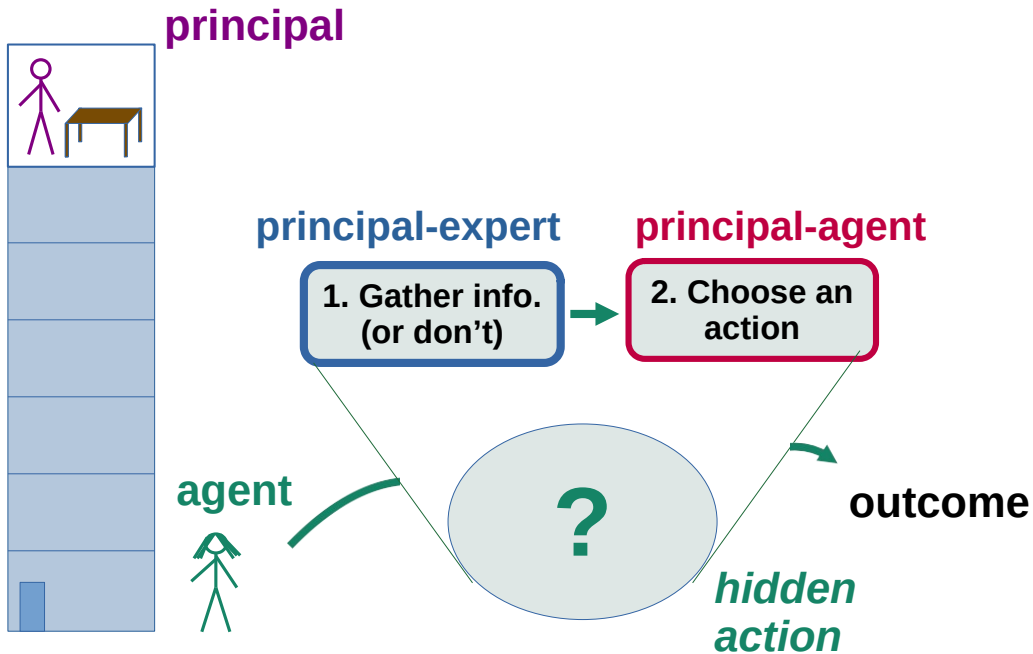


agent



*hidden  
action*

outcome



Zermeño (2012); Boutilier (2012); Oesterheld and Conitzer (2020)



# Outline

- 1 Model
- 2 Reducing to design of scoring rules
- 3 Special cases
- 4 Main result

# 1. Model

# Plan

- 1 Revisit standard **hidden action** model
- 2 Recall **information acquisition** model
- 3 Give **our model**

# Hidden Action - Model

- 1 Principal offers a **contract**  $t : \Omega \rightarrow \mathbb{R}$
- 2 Agent chooses an action  $a$ , incurs cost  $c_a$
- 3 Outcome  $\omega \sim p_a$  revealed, payment  $t(\omega)$ .

# Hidden Action - Model

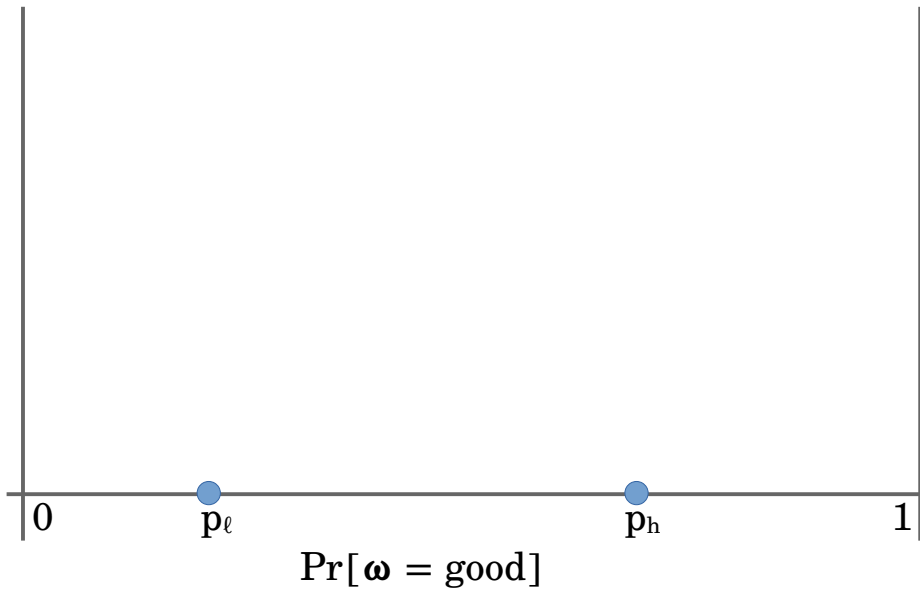
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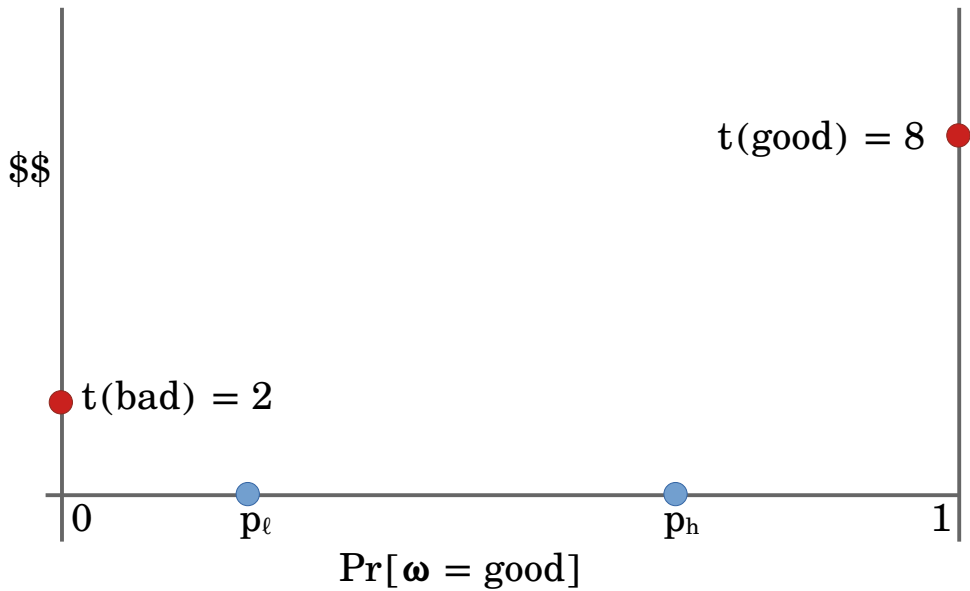
Require **limited liability**: payment  $\geq 0$  always.

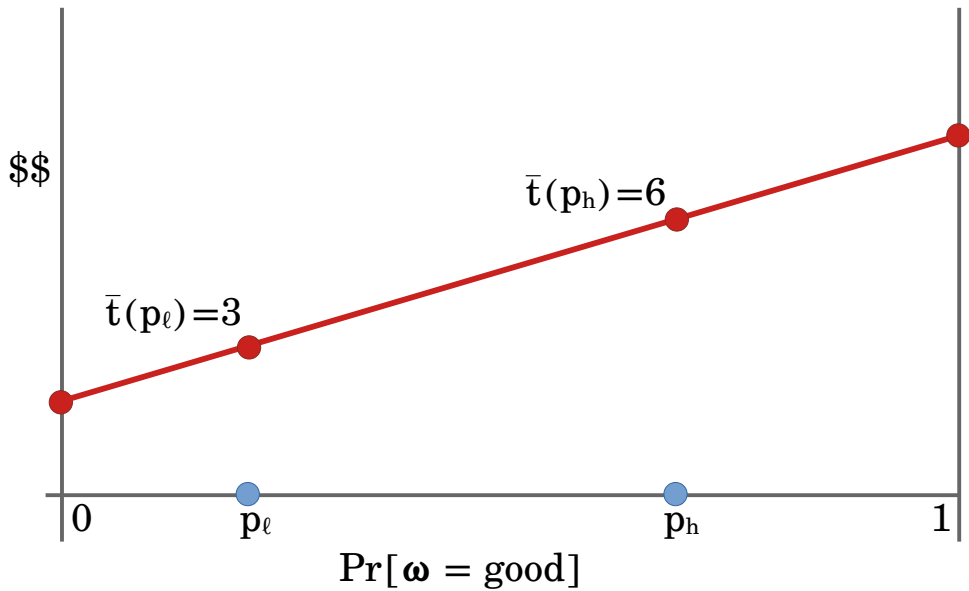
**Minimum payment problem**: incentivize  $a$  as cheaply as possible  
*agent maxes  $\mathbb{E}$  utility*



Related work: <https://sites.google.com/view/ec22-act-workshop>









# Information acquisition - model<sup>1</sup>

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<sup>1</sup>Related work: Li et al. 2022; Chen and Yu 2021; discussed later.

# Information acquisition - model<sup>1</sup>

- 1 Principal offers a scoring rule  $s : \Delta_{\Omega} \times \Omega \rightarrow \mathbb{R}$
- 2 Agent chooses whether to acquire signal for cost  $\kappa$
- 3 Agent reports a prediction  $p$
- 4 Outcome  $\omega$  is revealed, pay  $s(p, \omega)$ .

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**Observe:** prediction  $p$  yields **contract**  $t(\omega) = s(p, \omega)$ .

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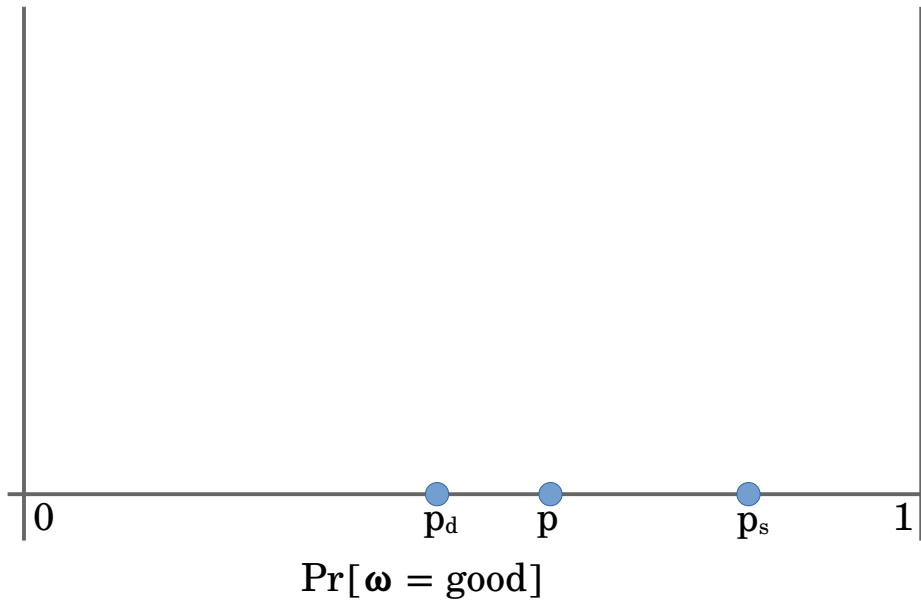
# Information acquisition - model<sup>1</sup> (take 2)

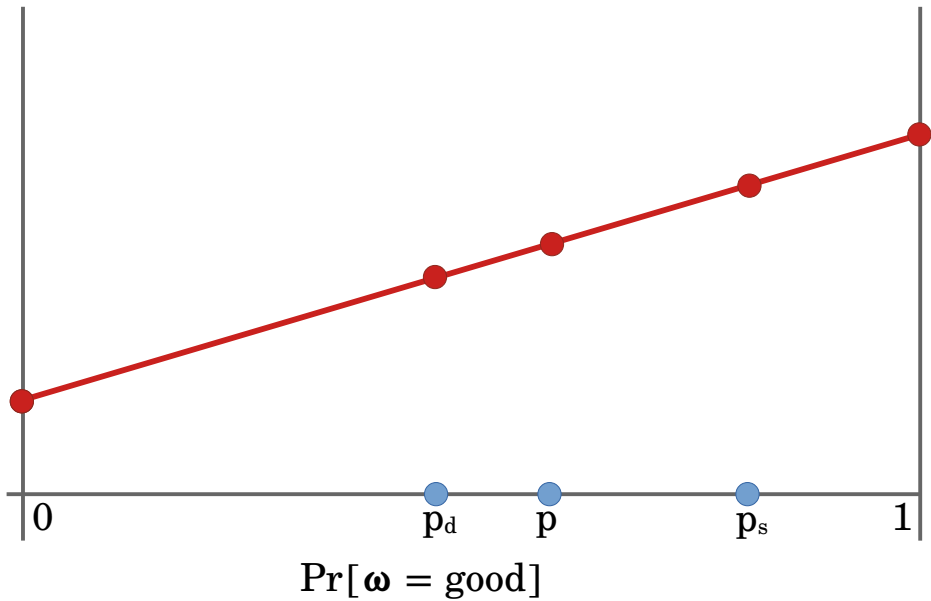
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**Principal offers a menu  $T$  of contracts**
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**Outcome  $\omega$  is revealed, pay  $t(\omega)$**

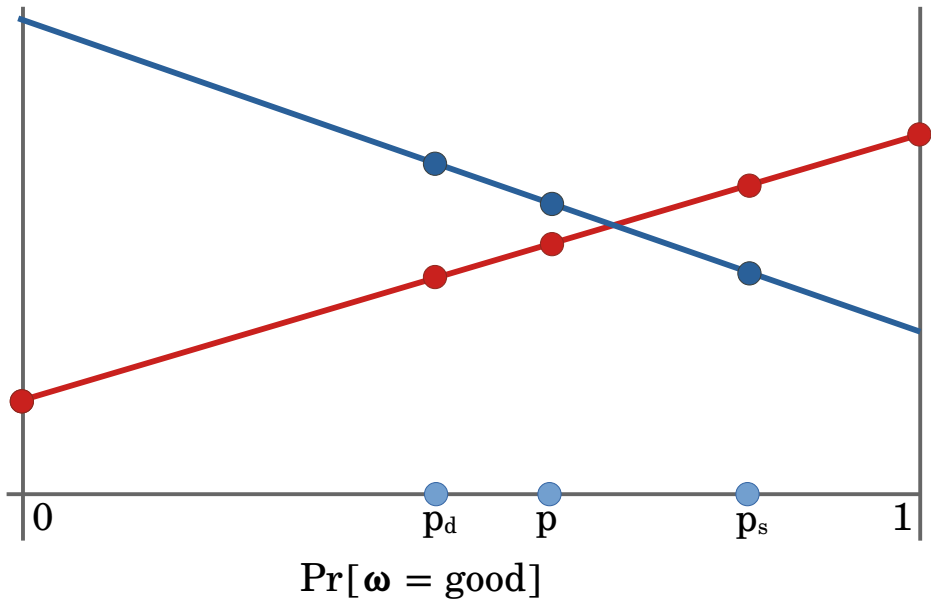
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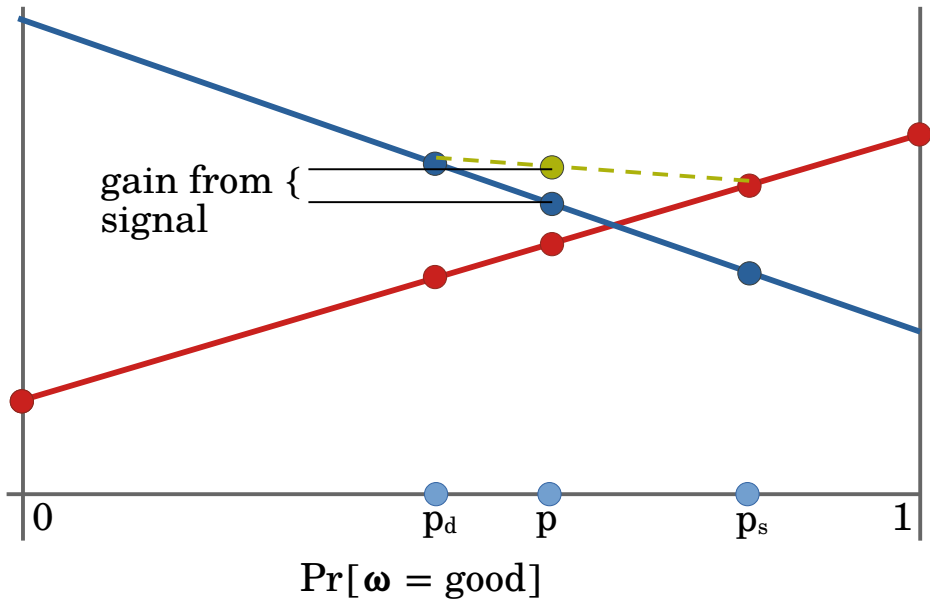
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# Our model

## *Contracts with Information Acquisition:*

- 1 Principal offers a menu  $T$  of contracts
- 2 Agent chooses whether to acquire signal  $S$  *cost  $\kappa$*
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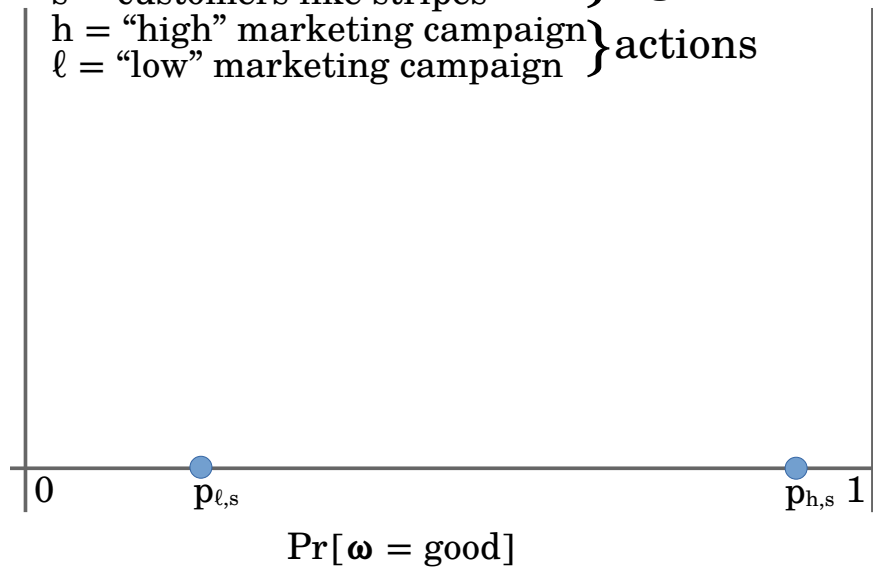
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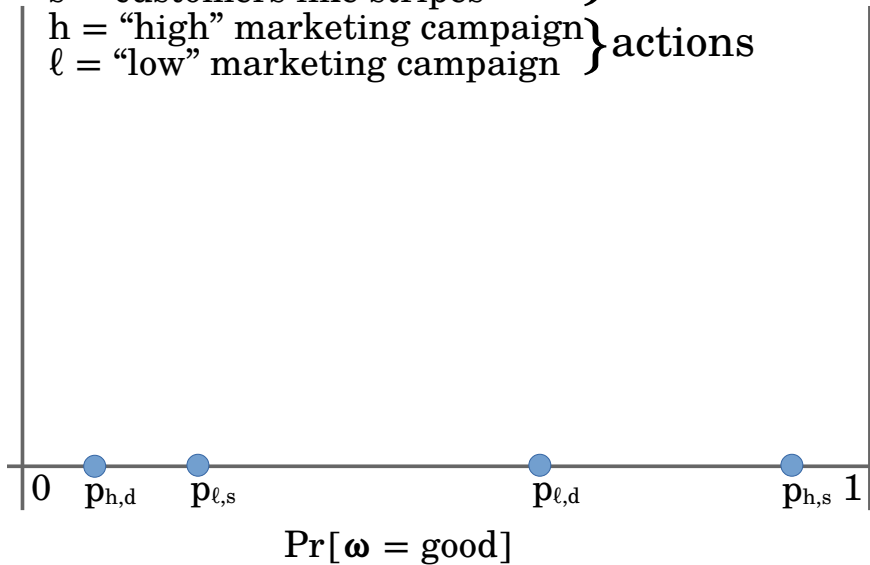
i.e. minimize expected payment subject to limited liability, IC, IR.

d = customers like polka dots } signal realiz.  
s = customers like stripes }  
h = "high" marketing campaign } actions  
l = "low" marketing campaign }



$d$  = customers like polka dots  
 $s$  = customers like stripes  
 $h$  = "high" marketing campaign  
 $\ell$  = "low" marketing campaign

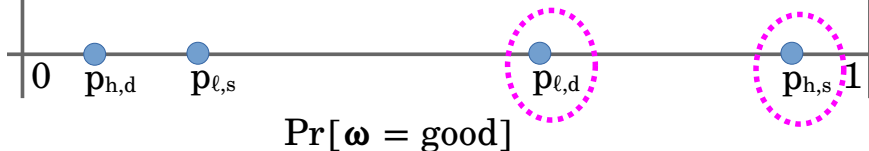
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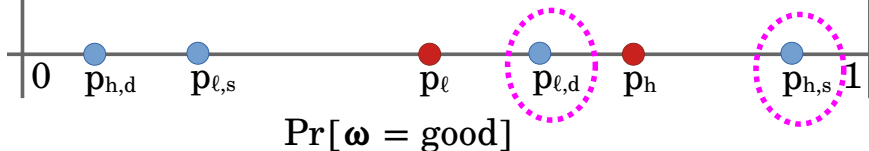
plan: if  $s$  then  $h$ ; if  $d$  then  $\ell$



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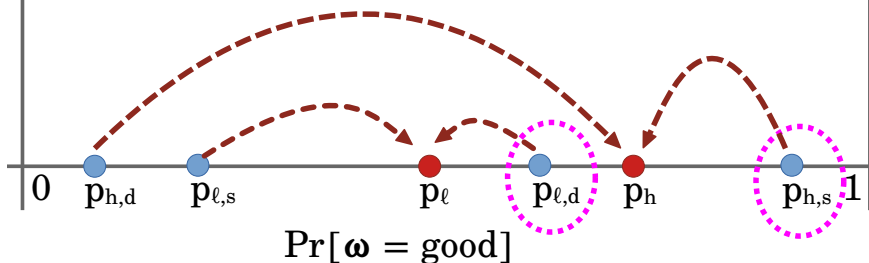
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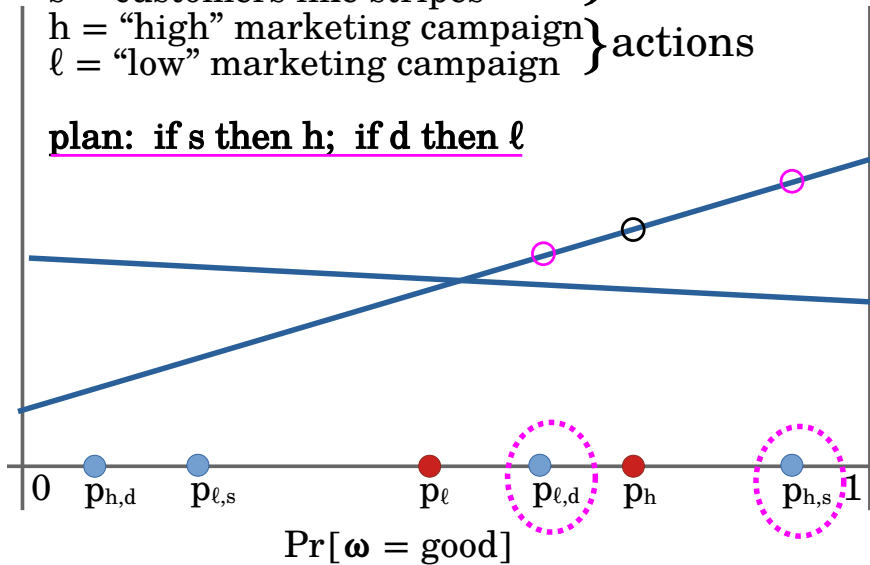
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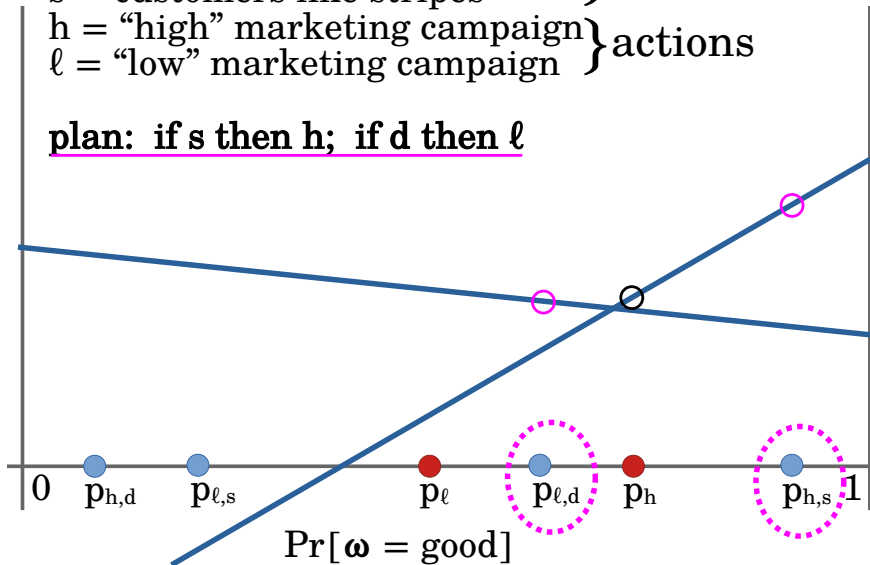
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## **2. Reducing to design of scoring rules**

# Key characterization

## Proposition

*WLOG, the menu  $T$  is a proper scoring rule  $s(p, \omega)$  and the agent reports their posterior belief  $p$  in Step 3.*

# Key characterization

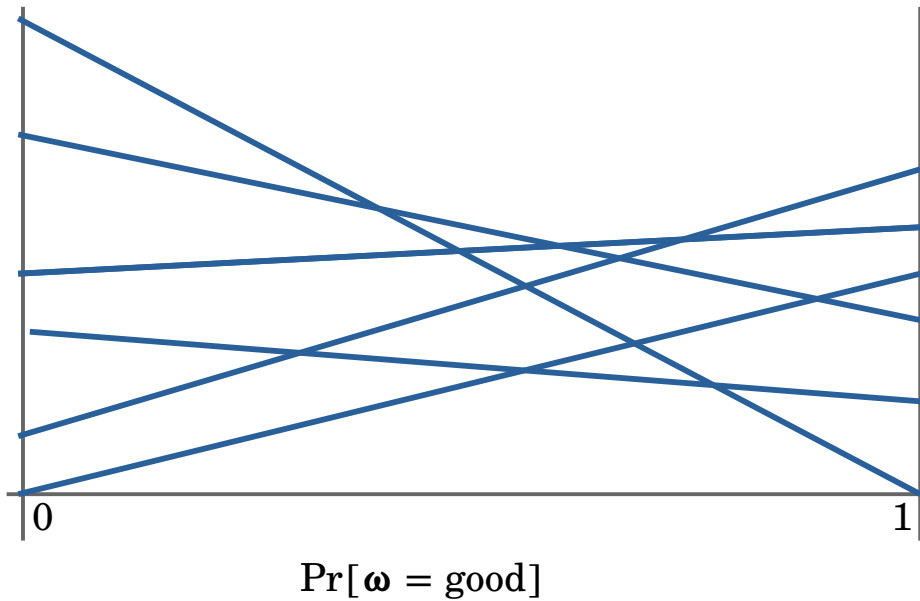
## Proposition

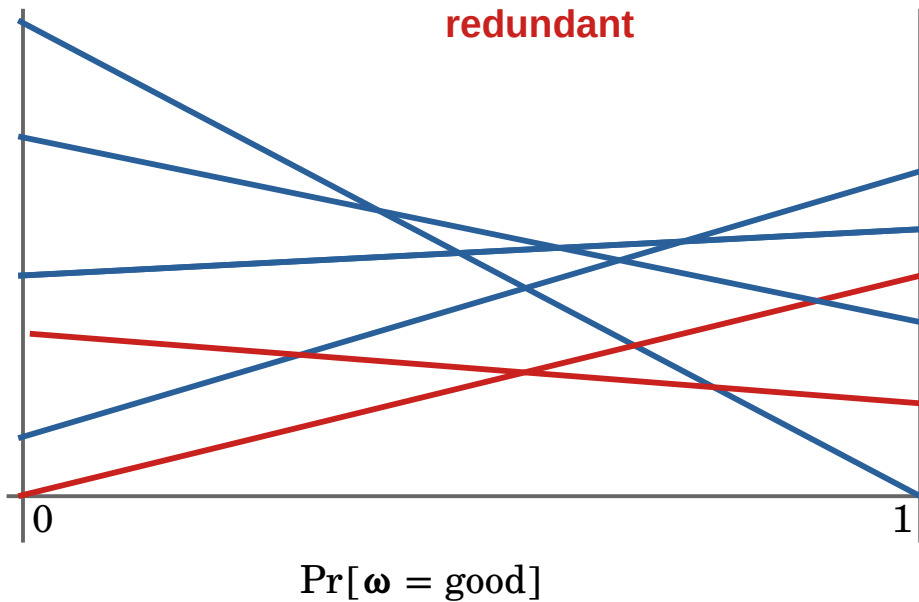
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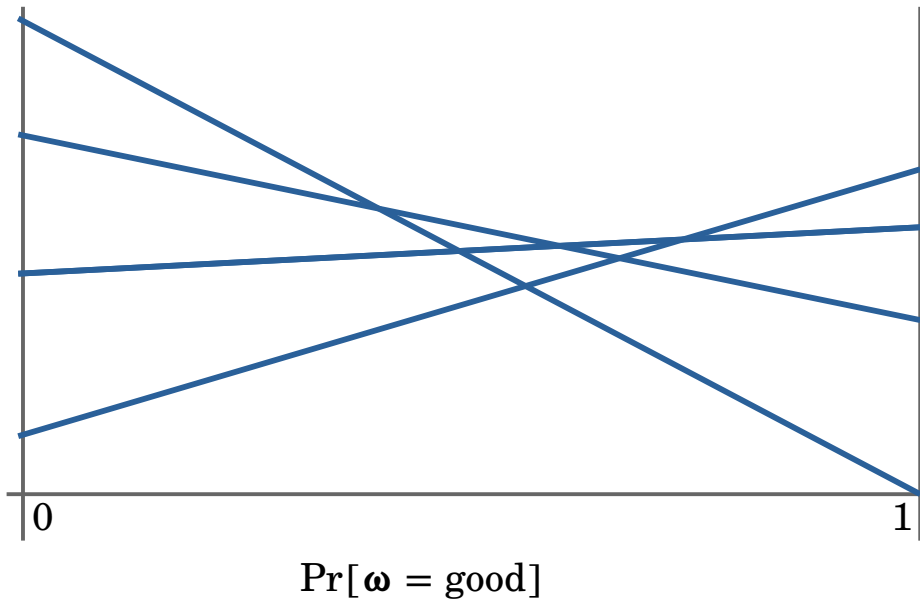
## Proposition (Restated)

*WLOG, the menu  $T$  is the set of subtangents of a subdifferentiable convex  $G : \Delta_\Omega \rightarrow \mathbb{R}$ , with*

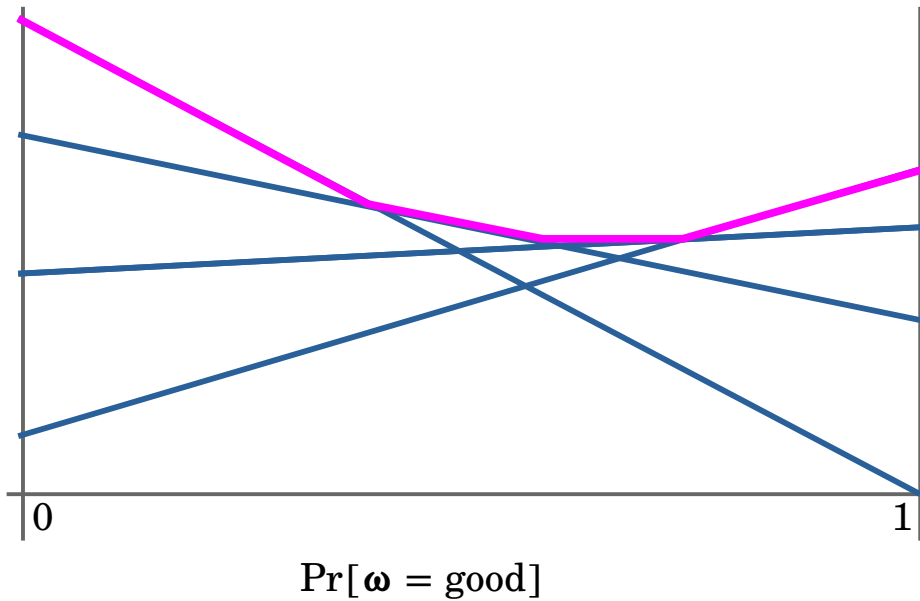
$$G(p) = \max_{t \in T} \bar{t}(p).$$

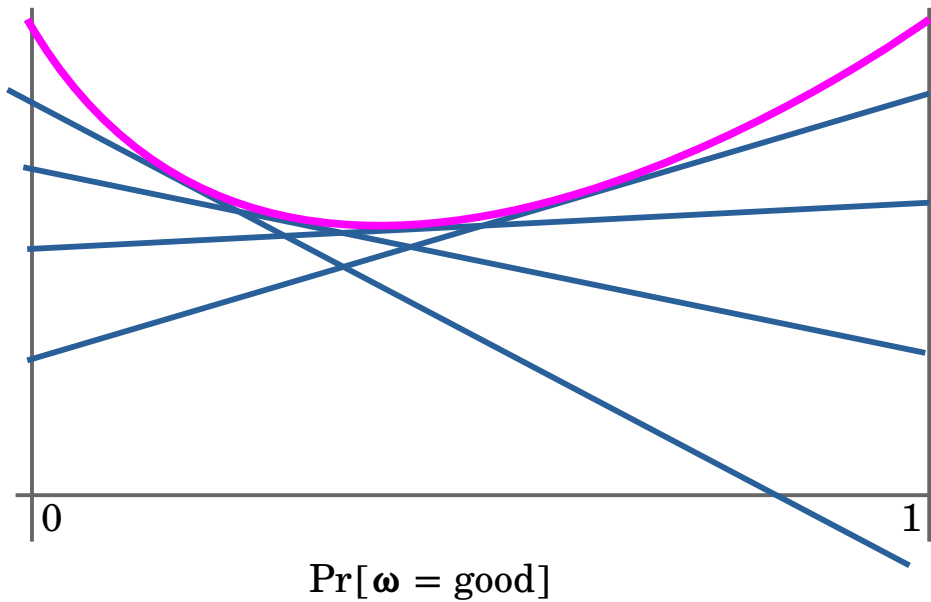












# 3. Special cases

# Recovering information acquisition

- 1 Principal offers menu  $T$
- 2 Agent chooses whether to acquire signal  $S$
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- 5 Outcome  $\omega \sim p_S$  is revealed, pay  $t(\omega)$

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*Known: under different constraints, "V" shape is optimal [Li, Hartline, Shan, Wu 2020-2022; Chen and Yu 2021].*

# Information acquisition - results

## Theorem

An optimal solution to the IA problem is  $G^*$ , where:

1 Define  $H(p) = \max_{\omega} \frac{p(\omega)}{p_0(\omega)}$ .

$p_0 =$  prior

2 Define  $G^*(p) = \frac{\kappa}{\mathbb{E} H(p_S) - 1} H(p)$ .

$\kappa =$  cost of signal

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**Observation:**  $G^*$  is a pointed polyhedral cone with its point at  $p_0$ .

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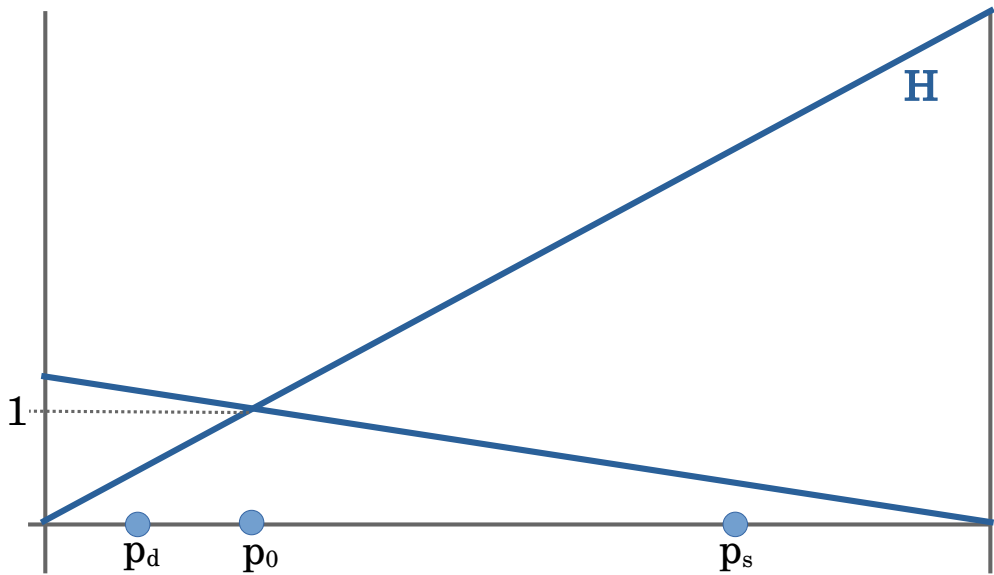
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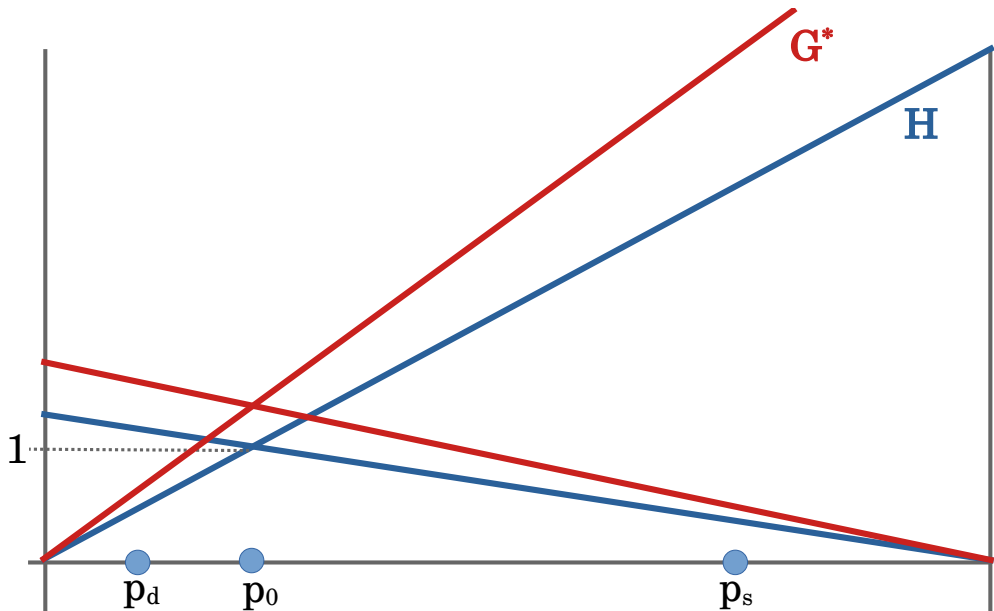
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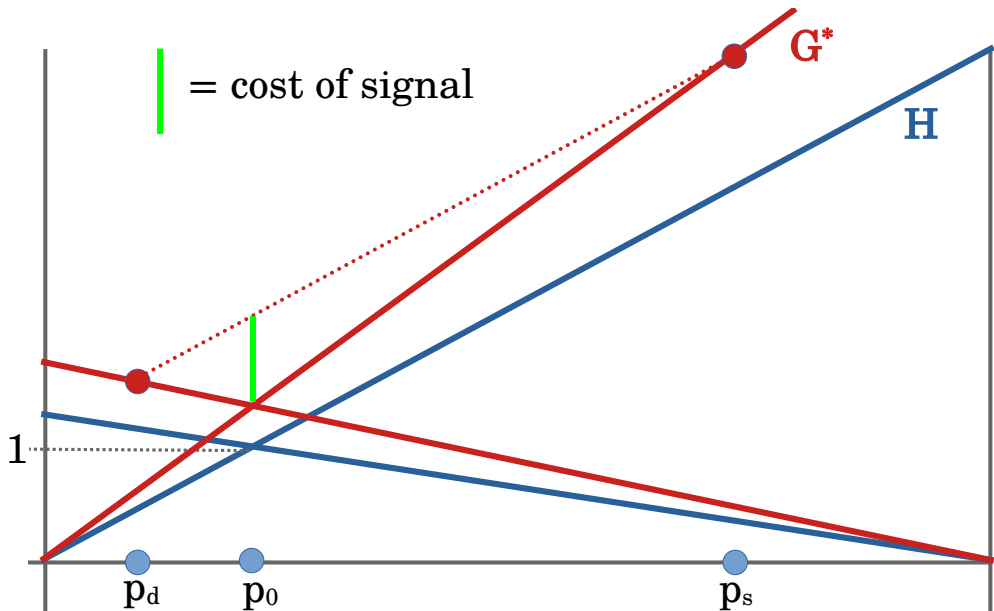
**Observation:**  $H$  contains all “indicator” contracts of the form

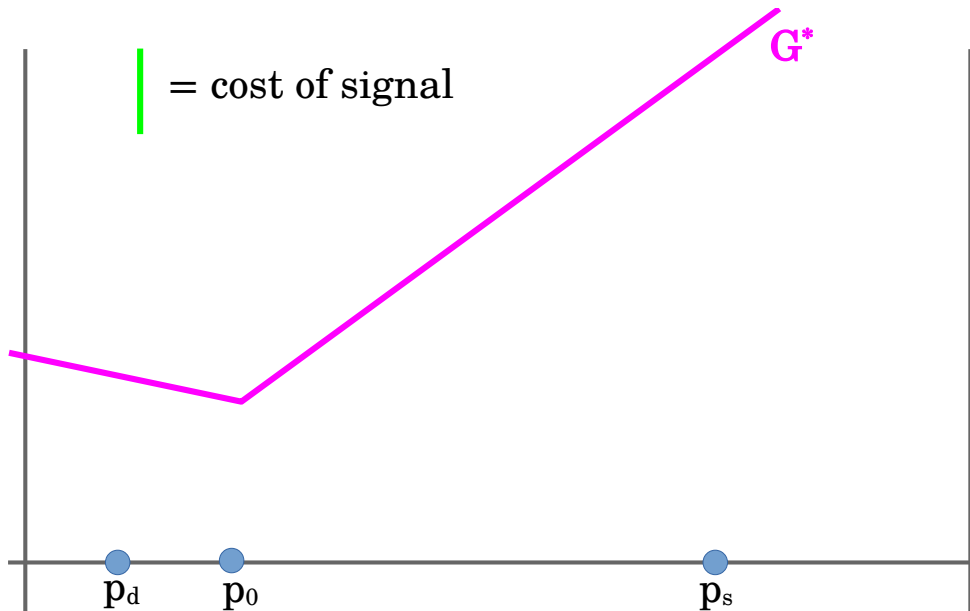
$$t_{\omega^*}(\omega) = \begin{cases} \frac{1}{p_0(\omega^*)} & \omega = \omega^* \\ 0 & \text{otherwise} \end{cases}.$$











# Proof idea

**Lemma:**  $H$  is feasible (respectively, optimal) on the right  $\iff$   
 $G = \frac{\kappa}{\mathbb{E}H-1}H$  is feasible (respectively, optimal) on the left.

$$\min_G \mathbb{E} G(p_S)$$

s.t.

$$\mathbb{E} G(p_S) - \kappa \geq G(p_0)$$

limited liability

$$\max_H \mathbb{E} H(p_S)$$

s.t.

$$H(p_0) \leq 1$$

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# Information acquisition - summary

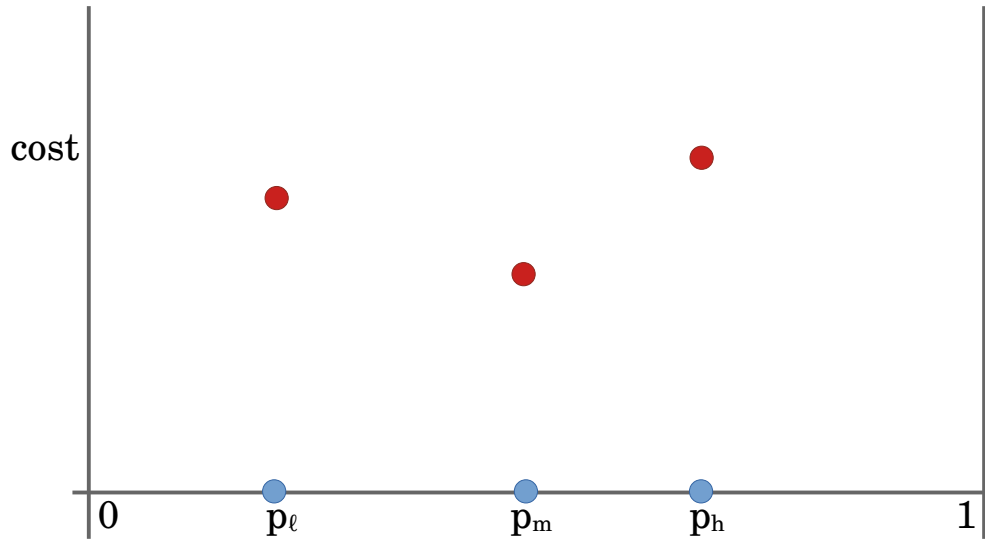
- Solve general multidimensional IA s.t. LL
- $G^*$  = polyhedral pointed cone
- Closed-form solution

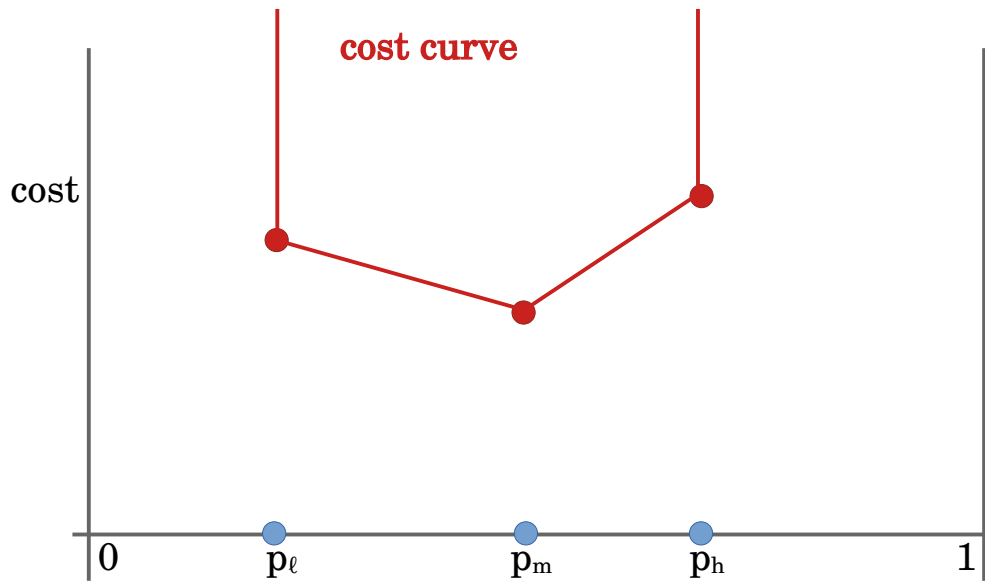
*as in prior work*

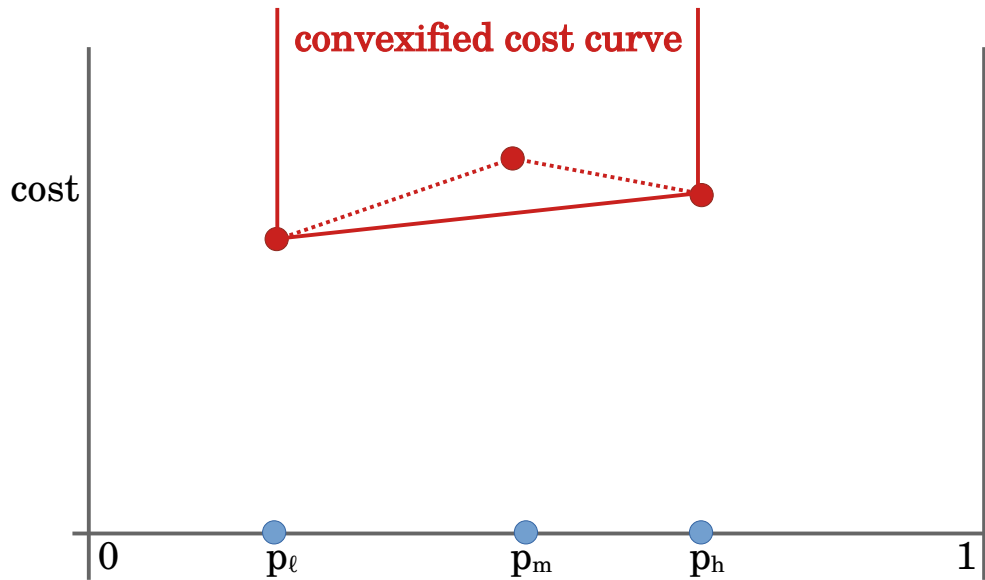
# Recovering the hidden action model

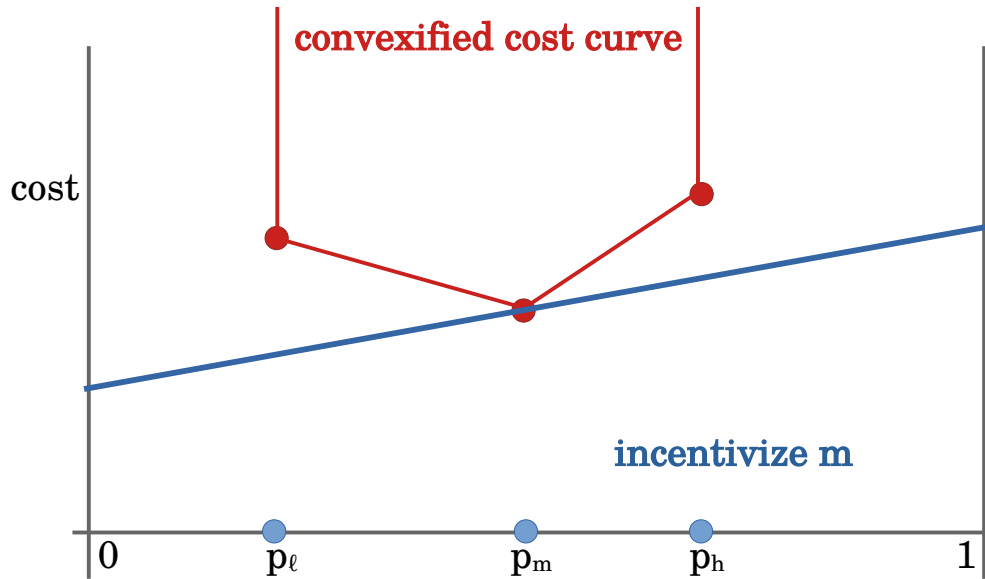
- 1 Principal offers menu  $T$
- 2 *(there is no signal)*
- 3 Agent selects contract  $t \in T$
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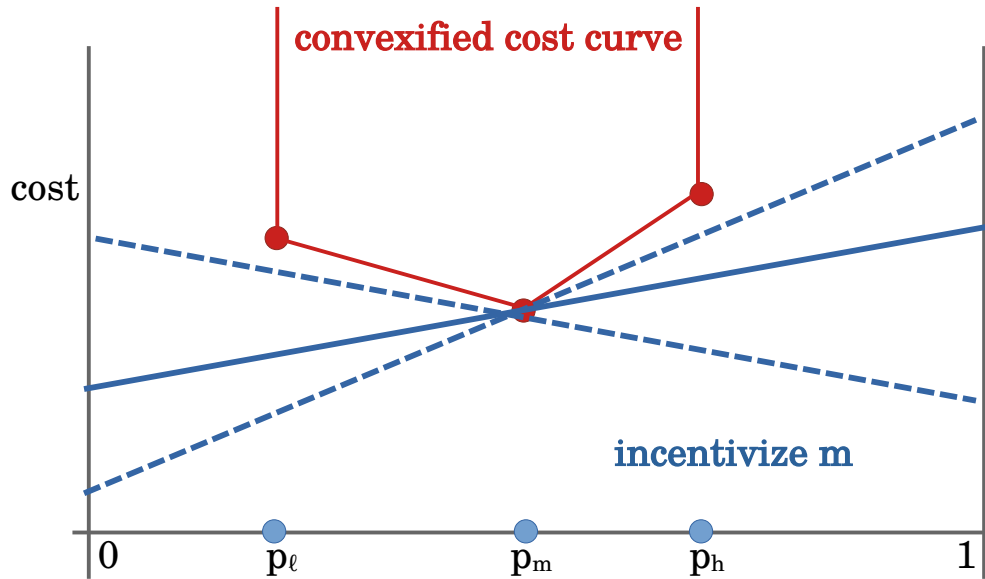


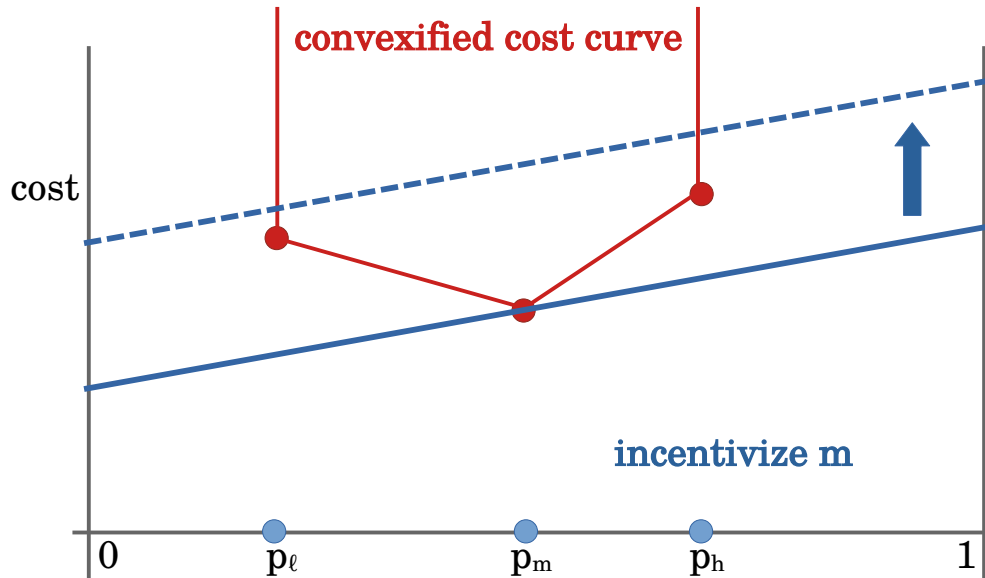


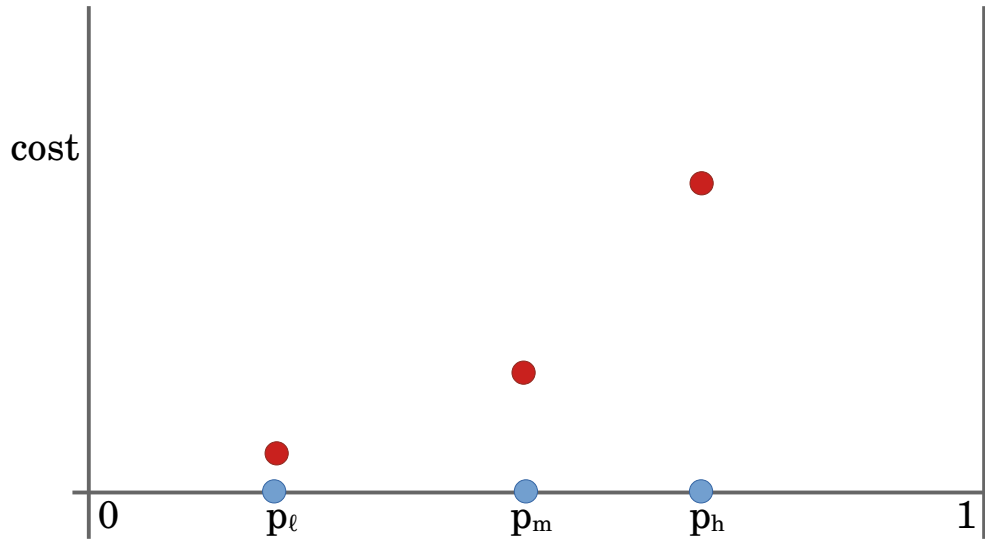


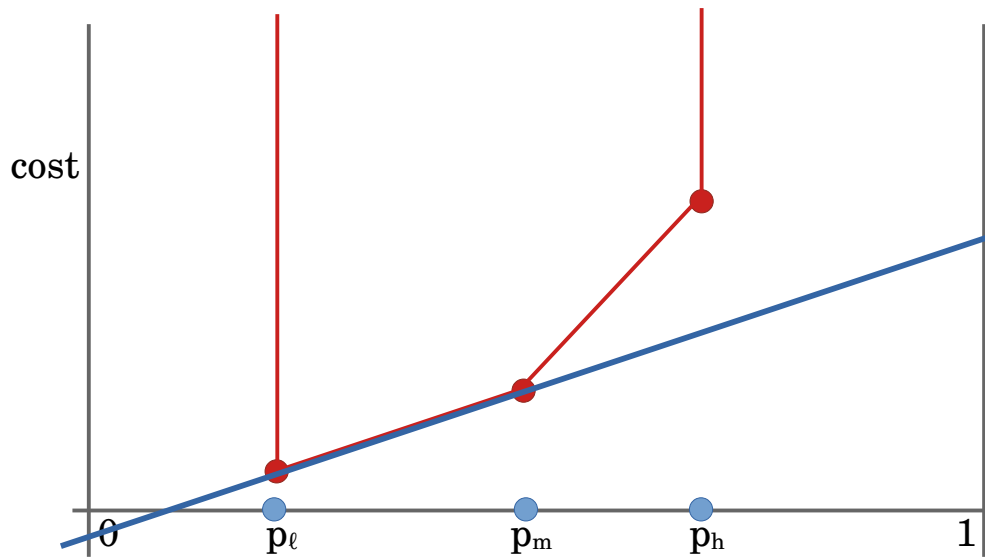




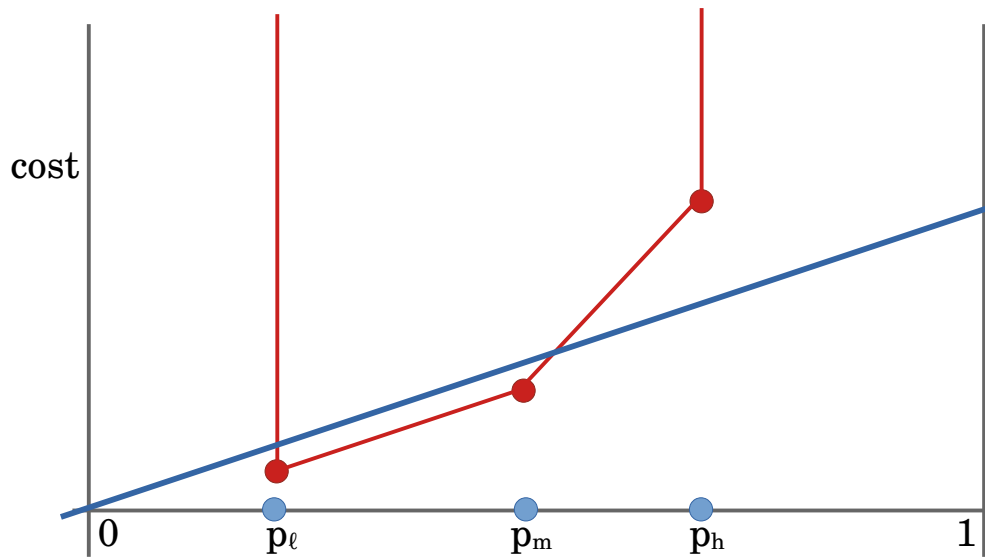












# Hidden actions - summary

- Study the **convexified cost curve**
- Geometric characterization of elicitable actions, optimal contracts
- **But**, no computational advantage over standard LP formulation
- **Still**, useful observations for our general model

## 4. Main result

# Main-ish result

## Theorem

*For Contracts with Information Acquisition, there is a polynomial-size linear program for computing an optimal menu for a given plan.*

Parameters: signal distribution  $q$ , action set  $A$ , posteriors  $\{p_{a,S}\}$ , plan  $f : S \rightarrow A$ .

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Key idea:  $G$  is WLOG piecewise linear with a small number of contracts.

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Key idea:  $G$  is WLOG piecewise linear with a small number of contracts.

**Extensions:** minimizing LP size;  
necessary conditions for feasibility of a plan.

# Conclusion

## Contributions:

- Model and LP for Contracts with Information Acquisition (IA)
- Scoring rule approach to contracts
- Closed-form sol'n for IA under limited liability

## Future work:

- Robustness
- Multiple signals
- Efficiently optimize principal utility

*see Oesterheld+Conitzer 2021*

*already unknown for IA*

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**Thanks!**